

# Dual characterizations of the sphere and the hyperbolic plane

Magdalena Caballero. University of Córdoba.

Joint work with Rafael M. Rubio. University of Córdoba.

**Abstract.** By means of a purely synthetic technique, we get a new characterization of the sphere without any curvature conditions, nor completeness or compactness. As well as a dual result for the hyperbolic plane, the spacelike sphere in the Minkowski space.

## Some classical characterizations of the sphere involving the curvature

In 1897 Hadamard proved

Any compact connected regular surface with positive Gaussian curvature in the three-dimensional Euclidean space  $\mathbb{E}^3$  is a topological sphere, [3].

His result motivated the search for conditions to conclude that such a surface is necessarily an Euclidean sphere. Two answers were given by Liebmann. The first one proved the rigidity of the sphere, conjectured by F. Minding in 1939.

If  $S$  is a compact and connected regular surface in  $\mathbb{E}^3$  with constant Gaussian curvature  $K$ , then  $M$  is a sphere of radius  $1/\sqrt{K}$ , [5].

Any compact and connected regular surface in  $\mathbb{E}^3$  with positive Gaussian curvature and constant mean curvature is a sphere, [6].

Another well-known characterization of the sphere involving the mean curvature is the Alexandrov theorem:

A compact and connected regular surface of constant mean curvature in  $\mathbb{E}^3$  is a sphere, [1].

## Dual results on the sphere and the hyperbolic plane involving the curvature

In the Minkowski space  $\mathbb{L}^3$ , the hyperbolic plane  $\mathbb{H}^2$  can be realized as one connected component of the hyperboloid of two sheets, and so it can be viewed as the spacelike (its induced metric is Riemannian) sphere in  $\mathbb{L}^3$ .

Hopf get the following dual characterizations of the spheres in  $\mathbb{E}^3$  and  $\mathbb{L}^3$ , [4].

The sphere is the only complete and simply connected regular surface in  $\mathbb{E}^3$  with positive constant Gaussian curvature.

The hyperbolic plane is the only spacelike regular surface in  $\mathbb{L}^3$  complete, simply connected and with negative constant Gaussian curvature.

In our paper we are interested in surfaces foliated by circles. In this direction, R. López proved the following dual results

A regular surface in  $\mathbb{E}^3$  with constant Gaussian curvature and foliated by pieces of circles is included in a sphere, or the planes containing the circles of the foliation are parallel, [7].

A regular spacelike surface in  $\mathbb{L}^3$  with constant Gaussian curvature and foliated by pieces of circles must be a portion of a hyperbolic plane, unless the planes of the foliation are parallel, [8].

## Our results - The sphere

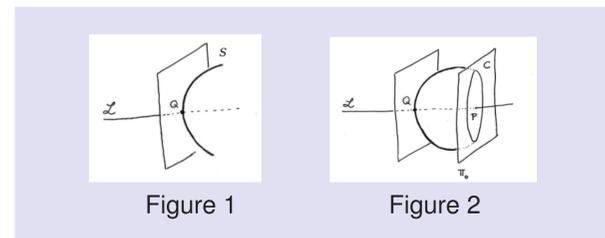
Let  $S$  be a connected regular surface in the Euclidean space  $\mathbb{E}^3$  such that its intersection with any affine plane is empty or a circle (including the case with radius zero), then  $S$  is necessarily an Euclidean sphere.

### The proof

Let  $Q \in S$  be an arbitrary point. We consider the tangent plane  $T_Q S$  and its normal line through  $Q$ ,  $\mathcal{L}$  (fig.1). We take the sheaf of affine planes with axis  $\mathcal{L}$  and we denote by  $\{C_i\}_{i \in I}$  the family of circles obtained when intersecting them with  $S$ .

We consider a plane  $\Pi_0$  parallel to  $T_Q S$  such that  $C = \Pi_0 \cap S$  is a non degenerate circle and we denote  $P = \Pi_0 \cap \mathcal{L}$  (fig.2). Then  $\Pi_0 \cap C_i \neq \emptyset$  for all  $i \in I$ , and the intersection points of each circle  $C_i$  with  $\Pi_0$  are the opposite points of a chord of  $C_i$  contained in  $\Pi_0$  with midpoint  $P$ . Therefore, the point  $P$  must be the center of  $C$  and as a direct consequence the circles  $C_i$  have all the same radius. Thus,

the sphere given by  $\bigcup_{i \in I} C_i$  is contained in  $S$ . We finish the proof thanks to the connectedness of  $S$ .



## Our results - The hyperbolic plane

Let  $S$  be a spacelike connected regular surface in the Lorentz-Minkowski space  $\mathbb{L}^3$  such that its intersection with any spacelike affine plane is empty or a circle (including the case with radius zero), then  $S$  is necessarily a hyperbolic plane.

**Remark 1** Notice that a circle in a spacelike affine plane  $\Pi$  of  $\mathbb{L}^3$  is the locus of the points in  $\Pi$  at a constant distance from a fixed point in  $\Pi$ , where the distance considered is the one associated to the induced metric.

### The proof (sketch)

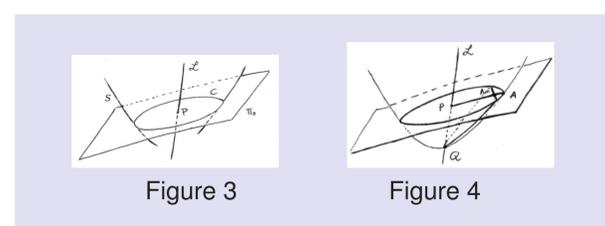
Let  $\Pi_0$  be a spacelike plane such that  $C = \Pi_0 \cap S$  is a non-degenerate circle. We denote its center by  $P$  and the normal line through  $P$  by  $\mathcal{L}$  (fig. 3).

Firstly, we prove that  $\mathcal{L} \cap S \neq \emptyset$ . We notice that  $S$  must be closed, and so we can take a point  $Q$  at which the distance from  $P$  to  $\mathcal{L} \cap S$  is attained.

For each  $A \in C$  and for each chord perpendicular to the segment  $AP$ , we call its midpoint  $A_m$  (fig.4). We can choose the chord as close to  $A$  as necessary so that the plane generated by it and the segment  $A_m Q$  is spacelike, we denote it by  $\Pi_{A_m}$ . We define  $\varepsilon_A$  to be the supremum (in the set of all possible chords satisfying the previous property) of the distance from  $A$  to  $A_m$ .

If  $\varepsilon = \min_C \varepsilon_A$ , we take  $0 < \rho < \varepsilon$  and for each  $A \in C$  we consider the chord with  $d(A_m, A) = \rho$ . Hence, all the circles  $\Pi_{A_m} \cap S$  (fig.4) have the same radius, and so there is a hyperbolic cap contained in  $S$  and containing  $C$ .

Finally, for each point  $A \in S$  there exists a spacelike plane intersecting  $S$  in a non-degenerate circle containing  $A$ . Therefore, there exists a hyperbolic cap contained in  $S$  and containing  $A$ . We finish the proof by using a connectedness argument.



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